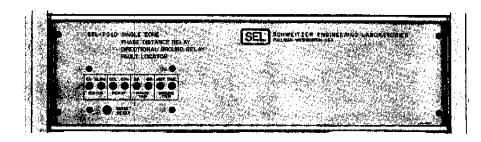


SEL-PG10

Also Available In LOW-PROFILE Package

SINGLE-ZONE
PHASE DISTANCE RELAY
GROUND DIRECTIONAL
OVERCURRENT RELAY
AND FAULT LOCATOR





- * ONE ZONE OF PHASE DISTANCE PROTECTION
- * INSTANTANEOUS GROUND OVERCURRENT PROTECTION
- * RESIDUAL TIME-OVERCURRENT ELEMENT WITH SELECTABLE CURVES
- * NEGATIVE- AND ZERO-SEQUENCE GROUND DIRECTIONAL ELEMENTS.
- * PHASE AND GROUND TIMERS PROVIDE ZONE OR BACKUP COORDINATION
- * PROGRAMMABLE OUTPUT LOGIC FOR FLEXIBLE APPLICATION
- * FIVE CONTACT INPUTS FOR MONITORING EXTERNAL EVENTS
- * FAULT LOCATING * EVENT REPORTING * METERING
- * AUTOMATIC SELF TESTING * RS232C COMMUNICATIONS

GENERAL DESCRIPTION

The SEL-PG10 ONE-ZONE PHASE DISTANCE RELAY AND GROUND DIRECTIONAL OVERCURRENT RELAY WITH FAULT LOCATOR provides a single zone of high-speed and time-delayed protection for transmission and distribution lines and cables. It combines a single-zone polyphase distance relay (21P) with a directional instantaneous residual-overcurrent relay and a time-overcurrent relay (67NI and 67NT), yet occupies less panel space than a single zone-packaged electromechanical distance relay.

It is designed to replace one electromechanical zone-packaged relay in upgrade applications where the benefits of backup ground protection, fault locating, event reporting, and remote communications are desired.

Because it occupies less panel space than common electromechanical distance relays, and since it is available in a vertical or horizontal form factor, retrofit is conveniently accomplished with very little effort.

Its low price makes it attractive for use as a fault locator or a backup relay. For backup applications, timers are included for delayed tripping initiated by the phase distance or the instantaneous residual-overcurrent elements.

The SEL-PG10 Relay Function Block Diagram illustrates the basic configuration of the protective capabilities.

Analog inputs from current and voltage transformers are delivered to the protective relaying elements and saved for additional features, such as metering and fault locating.

The relay elements process the analog data. Some intermediate logic is performed, such as overcurrent supervision of the mho elements and directional supervision of the residual-overcurrent elements.

The status of the intermediate results and some other information are recorded in the Relay Word.

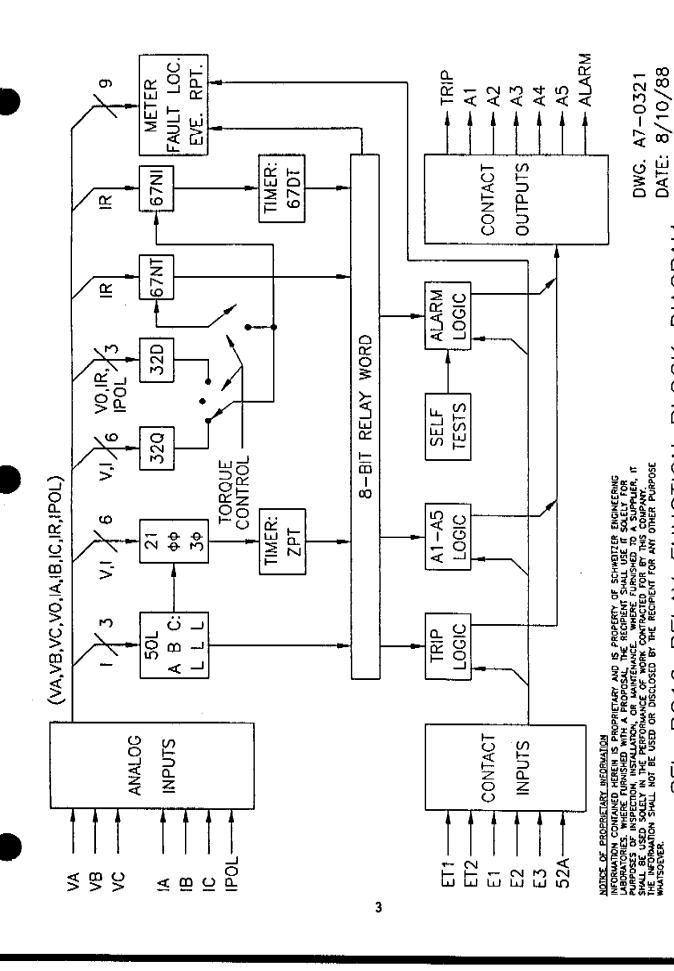
Logic for controlling the output relays uses the Relay Word data. Most of that logic is programmable by logic masks.

APPLICATIONS

The SEL-PGIO relay's event-reporting and fault-locating features economically provide valuable engineering and operating information, eliminating the need for event recorders and oscillographs in most applications. Its instrument transformer burden is negligible.

Time-Step Relaying

The SEL-PG10 relay provides one zone of time-step protection, with separate timers for phase and ground faults.



BLOCK DIAGRAM

FUNCTION

RELAY

SEL-PG10

Backup Relaying

The SEL-PG10 relay can be applied for phase and ground backup. Its programmability and remote-access capabilities allow the relay settings to be adjusted remotely to meet virtually any contingency.

In line terminals using electromechanical polyphase relays for phase-to-phase and three-phase faults, consider replacing one of the electromechanical relays with an SEL-PG10 relay to obtain phase distance AND ground directional overcurrent protection, fault locating, event reporting, and other features. No additional panel space is required, as the SEL-PG10 relay is available for vertical and horizontal mounting.

Fault Locating and Event Reporting

The SEL-PG10 relay is the most economical approach to adding fault locating and event reporting to line positions already equipped with adequate relaying.

SPECIFICATIONS

Relay Functions Mho characteristics for phase-phase and three-phase faults

One phase-to-phase zone One three-phase zone

Residual overcurrent protection for ground faults

One instantaneous element One definite time element

One time element with four selectable curve shapes

Negative- and zero-sequence directional elements for ground faults. Zero-sequence element is dual polarized.

Phase overcurrent elements supervise mho elements.

Relay Elements

Phase overcurrent:

50A, 50B, 50C (phase fault detectors)

Pickup: 0.5 to 40 A, +/- 0.1 A +/- 2% of setting.

Transient Overreach: 5% of set pickup.

Distance element specifications:

Phase distance:

21P: 0.125 to 32 ohms

Three-phase distance:

21ABC: 0.125 to 32 ohms

Torque Angle Setting: 47 - 90 degrees in one-degree steps.

Operating times:

Mho elements operate in 10 - 45 ms (25 ms

typical), including output relay delay.

A 0 - 2000 cycle timer is provided for the mho

elements.

Steady-state Error:

5% of set reach +/- 0.01 ohm at angle of maximum torque for V > 5 V and I > 2 A.

10% of set reach +/- 0.01 ohm at angle of maximum torque for 5 > V > 1 V and 0.5 < I < 2 A.

Mho Transient Overreach:

5% of set reach, plus steady-state error.

Mho Memory polarization:

Three-phase element is memory polarized using voltage from a four-cycle memory.

Ground Overcurrent:

67NT residual time-overcurrent element:

Selectable curve shape (4 curves).

Pickup: 0.25 to 6.3 A, 0.05 A +/- 2% of setting.

67NI residual-overcurrent element:

Pickup: 0.25 A to 48 times 67NT pickup. Transient overreach: 5% of set pickup.

A 0 - 2000 cycle timer is provided for the 67NI.

Ground Directional Elements:

Negative-sequence directional element:

Angle: same as mho element setting.

0.07 to 0.30 VA of negative sequence, Sensitivity: depending on distance relay settings, at max torque angle and V2 > 0.17V.

Zero-sequence directional element:

Voltage polarization:

Angle: same as mho element setting.

Sensitivity: (0.5 volts) * (51N pickup setting) in units of zero-seq. volts times residual amps and VO > 0.17V.

Current polarization:

Angle: Zero degrees.

Sensitivity: $(\bar{0}.5 \text{ amps}) * (51N \text{ pickup setting})$ in units of residual amps squared and Ipol > 0.5 amps.

Fault Location

Fault location is computed from event reports stored following each fault. Algorithm compensates for prefault current for improved accuracy for high-resistance faults.

Fault Reporting A data record is retained for each of the 12 most recent faults, which includes current, voltage, relay element, input contact and output contact information. The report may also be triggered by command or contact closure. When tripping occurs after the end of the event report, a second report is triggered at tripping.

Analog AC channel offset errors Self Testing

Stall timer monitors processor Power supply voltage checks

Setting checks

RAM, ROM, and A/D converter tests

Rated Input Voltage

115 volt nominal phase-to-phase, 3 phase 4 wire connection

Rated Input Current

5 amps per phase nominal 15 amps per phase continuous

390 amps for one second thermal rating

Output Contact Current

30 amp make per IEEE C37-90 para 6.6.2

6 amp carry continuously MOV protection provided

Logic Input Ratings

60 - 200 VDC for 125 VDC relays 25 - 60 VDC for 48 VDC relays Current = 6 mA at nominal voltage

Power Supply

125 Volt: 85 - 200 VAC or VDC; 12 watts

48 Volt: 30 - 60 VDC; 12 watts

Dielectric Strength Routine tested:

V, I inputs: 2500 VAC for 10 seconds

Other: 3000 VDC for 10 seconds (excludes RS-232)

Interference Tests

IEEE C37-90 SWC test (type tested)

IEC 255-6 interference test (type tested)

Impulse Tests

IEC 255-5 0.5 joule 5000 volt test (type tested)

RFI Tests

Type-tested in field from a 1/4-wave antenna driven by 20 watts at 150 MHz and 450 MHz, randomly keyed on and off, at a

distance of 1 meter from relay.

Dimensions

5 1/4" x 19" x 13". Mounts in standard 19" relay rack. Also

available for vertical mounting.

Unit Weight

21 pounds

Shipping Weight 32 pounds, including two instruction manuals

Operating Temperature -20 deg C to + 55 deg C

Burn-in

Each SEL-PG10 relay is burned in at 60 deg C for 100 hours

Temperature

Basic Protective Capabilities

The SEL-PG10 relay provides protection for transmission line faults of all types.

Three-Phase Faults:

The three-phase mho element is supervised by three overcurrent elements, which must all pick up. For positive action for close-in three-phase faults, four cycles of memory polarization are provided.

Phase-Phase Faults:

The phase-phase mho element is based on the compensator-distance principle, and has no response for three-phase faults. It is supervised by three overcurrent elements, of which at least one must pick up. A timer is provided which is driven by the phase-phase and three-phase mho elements. It may be used as a zone timer or as a backup-coordination timer. It may also be set to zero when no delay is required.

Ground Faults:

Ground fault protection consists of an instantaneous residual overcurrent element and a residual time-overcurrent element.

Directionality is determined by a negative-sequence directional element and a dual-polarized zero-sequence element. Settings select the negative-sequence element, or neither, either or both sources of zero-sequence polarization. To securely discriminate between forward- and reverse-direction faults, the directional elements have a torque threshold which must be exceeded before the fault direction is declared.

Four curve shapes (moderately inverse, inverse, very inverse, extremely inverse) of the residual time-overcurrent element are user-selectable. This element is either nondirectional or forward-reaching.

LOGIC DESCRIPTION

Relay Elements

single-phase overcurrent relays	50A 50B 50C	(phase fault detectors)			
three-phase mho distance line-line mho distance	21ABC 21P				
residual time-overcurrent pickup residual time-overcurrent trip residual inst-overcurrent	67NP 67NT 67N	T.C. or nondirectional T.C. or nondirectional T.C.			
negative-sequence directional zero-sequence dual pol directional	32Q 32D				

<u>Timers</u>

GTMR Ground timer for definite-time ground element

PTMR Phase-phase and three-phase fault timer

Enables From Setting Procedure

32QE Enables 32Q

32VE Enables voltage polarization of 32D 32IE Enables current polarization of 32D

67NTC Selects directional torque control for time-overcurrent relay

Contact Inputs

EXT1 External trigger 1 for event report
EXT2 External trigger 2 for event report

E1 Event 1 E2 Event 2 E3 Event 3

52A Circuit breaker monitor

Contact Outputs

TRIP Circuit breaker trip
Al Programmable output 1
A2 Programmable output 2
A3 Programmable output 3
A4 Programmable output 4
A5 Programmable output 5

ALARM System alarm

INTERMEDIATE LOGIC

The logic equations developed below represent combinations of the relay elements and other conditions. In the following equations the "*" indicates logical "and", and the "+" indicates logical "or".

50L = 50A + 50B + 50C Phase fault current supervision

3P50 = 50A * 50B * 50C Three-phase fault current supervision

ZABC = 21ABC * 3P50 Three-phase fault

ZP = 21P * 50L Phase-to-phase fault

DF = 320F * 320E + 32DF *

32IE + 32DF * 32VE + NOT(32QE + 32VE + 32IE) Forward direction

(If 32QE=32VE=32IE=NO then DF=1, i.e., disabling the directional elements makes the ground elements nondirectional.)

67NI = 67N * DF

ZPT = (ZABC + ZP) + PTMR

Phase or three-phase fault timeout

67DT - 67NI * GTMR

Definite-time ground timeout

RELAY WORD

Relay elements and intermediate logic results are represented in an eight-bit relay word. The user selects bits in this word to perform the desired functions for tripping or controlling the five programmable outputs. The selected bits are stored in masks for each function. The user programs the bits in these masks with the LOGIC command.

Relay Word:

50L ZABC ZP ZPT 67NP 67NT 67NI 67DT

The use of the relay word and programmable masks provides the user with great flexibility in applying the SEL-PG10 relay, without rewiring panels or changing jumpers on circuit boards.

OUTPUT EQUATIONS

The logic for controlling the TRIP output and five output relays (Al-A5) is programmable for flexibility and for testing. The logic is programmed by setting masks for various conditions, which are applied to the general relay word.

The general forms for each of the output equations follow:

Let R = relay word

MT = mask for trip

then: TRIP = R * MT

close TRIP - TRIP

open TRIP = NOT(TRIP) * NOT(52A + TARGET RESET button pushed) * (60 ms minimum TRIP)

A1 = R * MA1

A2 = R * MA2

A3 = R * MA3

A4 = R * MA4

A5 = R * MA5

The "*" symbol indicates logical "and", and the "+" indicates logical "or".

The function of the ALARM output relay is fixed. It responds to self-test failures, to setting changes, and to password violations.

SETTING PROCEDURE

The SET command invokes the relay setting procedure. Each setting is presented and prompted for in turn. If a new setting value is desired, it is entered in response to the appropriate prompt, while just pressing carriage return retains the old setting and prompts for the next one.

In the example shown, only the XO value was changed. It was changed from 259.40 to 248.57. Note that the new value of 248.57 is presented at the end of the procedure before enabling, along with all other settings. This provides a final inspection for typographical or other errors.

As a convenience, the operator could have typed END in response to the prompt for Line Length (or any other setting except Relay ID), and gone directly to the final presentation of settings, without having to scroll through the rest of the prompts.

->>SET

SET clears events. CTRL-X cancels. Enter data, or RETURN for no change

```
: Example 230 kV Line
                                   ?
ID
    : (Ohms pri)..... = 13.90
                                   ?
R1
    : ..... = 79.96
                                   ?
Xl
    : ..... = 41.50
                                   ?
RO
    : ..... = 259.40
                                   ? 248.57 <- operator changes XO
XO
                                          <- could type END here
    : Line Length (mi).... = 100.00
PTR : .... = 2000.00
MTA : Max Torque Angle (deg) = 80.80
                                   ?
                                   ?
LOCAT: Locate faults (Y/N)... = Y
                                   ?
   : Reach (% line)..... = 80.00
                                   ?
PTMR : Dly-Phase (cyc)..... = 0.00
50L : PU (Amps pri)..... = 100.00
                                   ?
67NP : PU (Amps pri)..... = 100.00
67NTD: Time Dial..... = 3.00
67NC : Curve (1,2,3,or4).... = 2
                                   ?
67NTC: Torque Ctrl (Y/N) .... = Y
                                   ?
67NIP: PU (Amps pri)..... = 1000.00
                                   ?
GTMR : D1y-Gnd (cyc)..... = 0.00
                                   ?
32QE : Enable (Y/N).... = N
32VE : ..... - Y
32IE : ..... = Y
TIME1: Port 1 timeout (min).. = 5
                                   ?
TIME2: ..... # 0
AUTO : Auto port (1,2)..... = 2
                                   ?
RINGS: (1-30).... = 3
```

New settings for: Example 230 kV Line

R1 -13.90	X1 - 79.96	RO =41.50	XO =248.57	LL	=100.00
CTR =200.00	PTR =2000.00	MTA =80.80	LOCAT=Y		
Z% =80.00	PTMR -0.00	50L =100.00			
67NP =100.00	67NTD=3.00	67NC =2	67NTC-Y		
67NIP=1000.00	GTMR =0.00				
320E =N	32VE =Y	32IE =Y			
TIME1=5	TIME2=0	AUTO =2	RINGS=3		

OK (Y/N) ? Y Please wait... Enabled

SAMPLE EVENT REPORT

Example 230 kV Line

Date: 7/28/88

Time: 11:22:11.329

F10=SEL-PG10-R100-V656mpc-D880724

	c	urrents (amps)				Voltage (kV)	:5		Outputs	•
IPOL	IR	AI	IB	IC	VA	VB	VC	52266 01177 P3PIT	TAAAAAA P12345L	
3 -3 -3 0	0 4 0 -3	799 -101 -796 98	-305 736 302 -739	-481 -632 485 626	132.8 -16.0 -132.8 16.0	-52.1 123.0 52.0 -123.0	-80.8 -106.7 80.9 106.7	* * *		*
6 0 -3 0	- l 3 1 -4	796 -101 -793 104	-302 739 305 -736	-481 -629 481 636	132.9 -16.1 -132.8 16.1	-52.0 123.0 52.1 -123.3	-80.9 -106.5 80.9 106.3	* * *		******
-3 3 3 -3	1 4 -2 -3	787 -98 -790 98	-308 736 308 -739	-488 -629 488 626	132.9 -16.2 -132.9 16.2	-51.8 123.2 51.8 -123.1	-80.7 -106.5 -80.8 106.6	* * *	******	*****
0 -3 3 3	1 93 45 -620	793 3 -551 -591	-305 683 160 -374	-485 -591 440 349	132.8 -16.7 -122.4 14.2	-51.9 122.8 56.3 -123.9	-80.9 -106.7 85.2 105.7	‡p	******	*****
-6 3 3 -3	129 1173 -371 -1309	349 1186 -396 -1306	-13 69 3 -6	-223 -79 25 9	104.6 -11.4 -96.1 11.6	-63.6 125.2 67.1 -125.1	-92.5 -104.5 -96.2 104.4	*P *P **P	**.*.	*
0 -3 0 3	397 1329 -402 -1330	400 1318 -396 -1325	3 -3 -3 3	-6 0 6 -3	94.9 -11.7 -94.7 11.7		-96.7 -104.2 96.6 104.2	*,,*p *,,*p *,,*p	*, *, *, *, *, *, *, *, *, *, *, *, *, *	*****
0 3 0 -3	403 1328 -402 -1329	400 1328 -406 -1321	0 0 0 3	0 3 -3 -6	94.7 -11.6 -94.8 11.7	125.3		**p **p **p	**.*.	
0 0 0	402 1330 -402 -1330	406 1318 -406 -1318	-3 0 0 -3	6 -6 -3	94.8 -11.9 -94.7 11.8	125.2	-104.1 96.6	**P **P **P	*, *, *, *, *, *, *, *, *, *, *, *, *, *	
-3 0 6 0	403 1238 -449 -711	400 1230 -440 -705	3 0 0 0	3 0 3 0	94.9 -11.4 -105.1 13.9	125.4	-103.9 92.3	**P **P *P	*,,*,*, *,,*,*, *,,*,*,	*****
-6 3 0 -3	276 155 -32 -20	271 151 -28 -25	3 0 -6 0	-3 -3 0	122.6 -16.6 -131.5 16.5	123.2	-106.5 81.8	*P *P *P	···*···	
6 -3 -3 6	3 2 1 -1	6 6 -3 3	3 0 0 3	3 0 0 -3	-132.	5 123.	5 -106.1 4 - 8 1.2			

Event : AG Location : 50.06 ml 4.06 ohms sec Duration: 6.00 Fit Current: 1382.3

R1 =13.90 X1 =79.96 R0 =41.50 CTR =200.00 PTR =2000.00 MTA =80.80 2% =80.00 PTMR =0.00 50L =100.00 67NP =100.00 67NTD=3.00 67NC =2 67NIP=1000.00 GTMR =0.00 32QE =N 32VE =Y 32IE =Y TIME1=5 TIME2=0 AUTO =2 X0 =248.57 LL =100.00 LOCAY+Y 67NTC-N RINGS-3

Logic settings:

MT MA1 MA2 MA3 MA4 MA5 66 40 20 08 04 02

EXPLANATION OF EVENT REPORT

Example 230 kV Line

Date: 7/28/88

Time: 11:22:11.329

FIO=SEL-PG10-R100-V656mpc-D880724

Currents (amps)						Voltage (kV)	Relays	Outputs Inc	Inputs	
IPOL	İR	AI	TR	ic	VA	VB	vc	52266 01177 P3PIT	TAAAAAA EEE P12345L TT1 12	232
3 3	45 -620	-551 -591	160 -374	440 349	-122.4 14.2	56.3 -123.9	85.2 105.7	* ;		:: *
-6 3 -3	1173 -371	349 1186 -396 -1306	-13 69 3 -6	-223 -79 25 9	-11.4 -96.1	-63.6 125.2 67.1 -125.1	96.2	*P	** ** **	
Event Duratio	: AG on: 6.00	Locat F1t C	ion : urrent:	50.06 1382.		.06 o	hms sec			
CTR =: Z% =: 67NP =:	13.90 200.00 30.00 100.00 1000.00		.00	RO MTA 50L 67NC	-41.50 -80.80 -100.00 -2	XO LOCA 67NT		' LL	-100.00	
320E -1 TIME1-!	V	32VE =Y TIME2=0		321E AUTO		RING	S=3			

Logic settings:

MT MA1 MA2 MA3 MA4 MA5 66 40 20 08 04 02

Currents and voltages are in primary Amps and KV. Rows are 1/4 cycle apart. Time runs down page. Obtain phasor RMS value and angle using any entry as Y-component, and the entry immediately underneath as the X-component. For example, from bottom rows, IAY = -396, IAX = -1306. Therefore, IA = 1365 amps RMS primary, at an angle of ATAN(-396/-1306) = -163 degrees, with respect to the sampling clock.

```
<FID>
                                                                      Firmware Identification Data
                                                                      Columns show states of internal relay elements
    <Relays>
                                                                                                                                                                                                                                                                                                        ---> Designators
                                                                             50P: phase overcurrent ....: 50L
213: 3-phase distance .....
                                                                                                                                                                                                                                                                                                          ---> *
                                                                                                                                                                                                                                                                                                          ---> *
                                                                             21P : 2-phase distance .....
67I : inst ground overcurrent : 67NI
                                                                                                                                                                                                                                                                                                           ---> *
                                                                                                                                                                                                                                                                                                         ---> *
                                                                 D/I: ground time-overcurrent ---> P.T

Columns show states of output contacts: ON = "*", OFF = "."

TP=TRIP, A1-A5=PROGRAMMABLE, AL=ALARM

Columns show states of input contacts: ETI=EXTERNAL TRIGGER 1,

ET2=EXTERNAL TRIGGER 2, E1-E3=EXTERNAL EVENT, 52A=PCB A-CONTACT

Fault type indication is one of the following:

AG, BG, CG = single-phase, AB, BC, CA = 2-phase
  <Outputs>
  <inputs>
   <Event>
                                                                  AG, BG, CG = single-phase, AB, BC, CA = 2-phase,
ABG, BCG, CAG = 2-phase to ground, ABC = 3-phase
followed by a "T" if a TRIP triggered the report
Other indication is EXT = externally or otherwise triggered
Distance to fault is # 100,0000 is indicated.
Other indication is EXT = externally or otherwise triggered
Cohms sec>
Couration>
Couration
Couration>
Couration
Couration
Couration
Couration
Couration detarmined from relay element(s) pickup time
Max phase current (primary amps) taken near middle of fault
Primary series impedance settings for transmission line
Line length corresponding to specified line impedances
Couration>
Couration>
Couration>
Couration
                                                                    Phase-overcurrent setting
  50L
  67NP,TD,C,TC
                                                                 GND time-overcurrent Pickup, Time-Dial, Curve, Torque Control Ground instantaneous-overcurrent pickup setting
  67NIP
GTMR
320E,VE,IE
TIME1,2
                                                                 Ground timer for ground faults
Ground fault directionality from (V2,I2), or (V0/IP,I0)
Communications port timeout intervals (automatic log-off)
Port assignment for automatic message transmissions
 AUTO
                                                                  Number of rings to wait before modem answers telephone
  <Logic settings> See LOGIC command for a description of mask settings
```

SAMPLE COMMAND DISPLAYS

->>HISTORY

The date, time, and type of event are shown for each of the twelve most recent events. If the event is a fault, the distance, duration, and current are shown. An example of the display is shown below:

Date: 7/28/88

Time: 01:45:40

Example 230 kV Line

TIME TYPE DIST **CURR** DATE DUR 09:03:01.092 7/28/88 AG 100.21 7.25 798.1 2 7/28/88 09:02:11.167 AG 74.97 4.00 1022.0 3 7/28/88 09:02:10.962 AG 25.21 7.25 2120.9 4 7/28/88 09:00:13.345 BC 25.52 7.25 3167.6

10 11 12

Note that only four events have occurred since the relay was set or powered on.

=>>METER

I (A) 994 995 994 1723 1724 1724 V (kV) 134.4 134.3 134.2 233.1 232.8 232.9

P (MW) 350.91 Q (MVAR) 67.82

 ${\bf P}$ and ${\bf Q}$ are positive when the power flow is in the direction of the reach of the relay, i.e., out from the bus and into the line.

=>>STATUS

Example 230 KV Line Date: 7/28/88 Time: 11:04:56

SELF-TESTS

W=Warn F=Fail

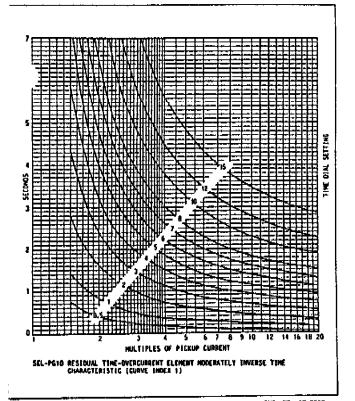
ΙP IR IA ΙB IC VA VC 0\$ 2 0 0 2 4 -2 -2 -2 PS 4.99 15.14 -14.85RAM ROM A/D MOF SET OK OK OK. OK OK

=>>TARGETS

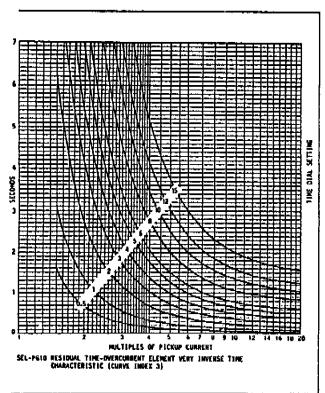
The eight-LED display on the front panel can be programmed to show targets (default), Relay Word bits, contact inputs and contact outputs, as shown below. This feature is especially useful for testing individual relay elements.

LED:	1	2	3	4	5	6	7	8	
N									
0	EN	ALRM	50L	67N	3-PH	2-PH	INST	TIME	RELAY TARGETS
1	50L	ZABC	ZP	ZPT	67NP	67NT	67NI	67DT	RELAY WORD #1
2			52A	E3	E2	E1	EXT2	EXT1	CONTACT INPUTS
3		TRIP	A1	A2	A3	A4	A5	ALRM	CONTACT OUTPUTS

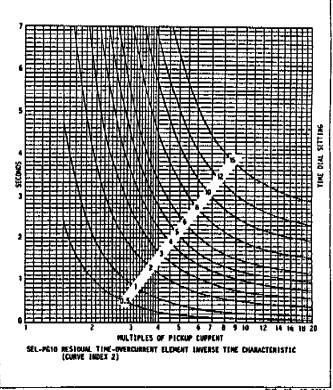
The front panel targets can be reset and cleared remotely or locally using the target command. Type "TARGET R <RETURN>" to reset and clear the targets.



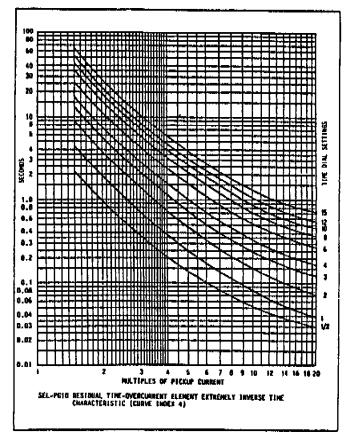




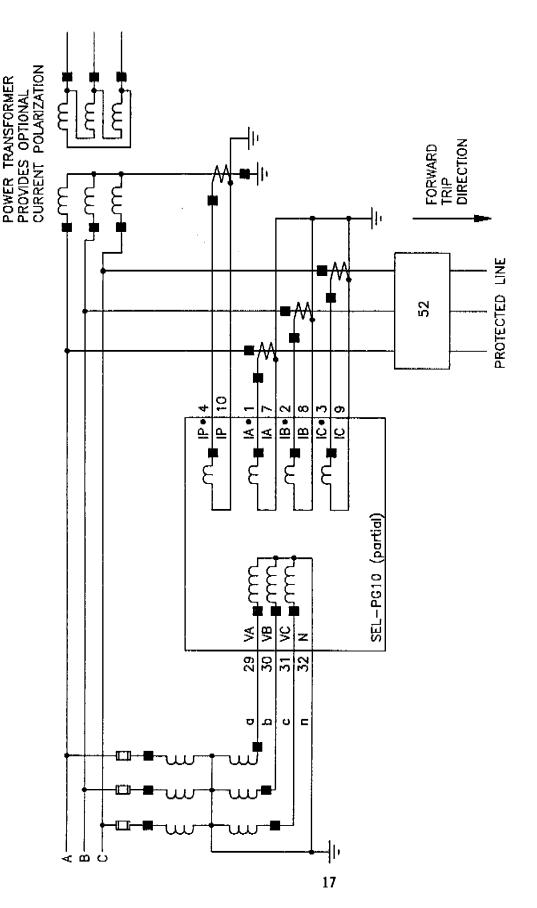
046. MO. A7-0362 0ATE: 09-13-88



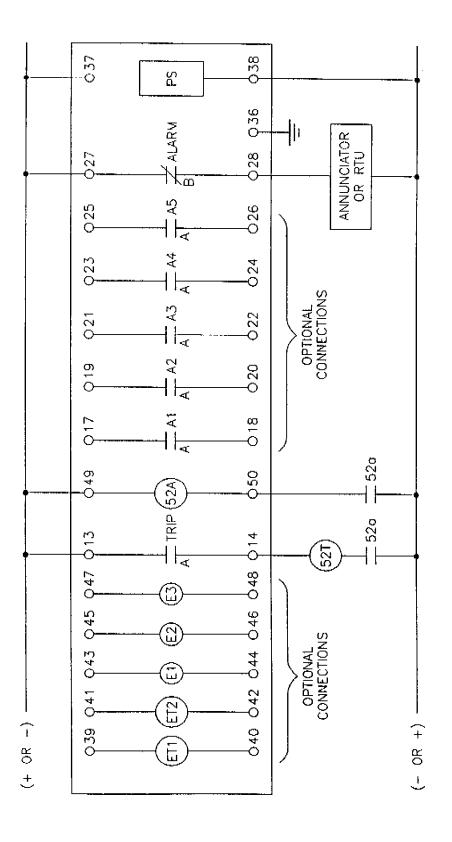
DMG. NO. A7-0361 DATE: 09-13-68



DMG. NO. A7-0363 DATE: 09-13-60



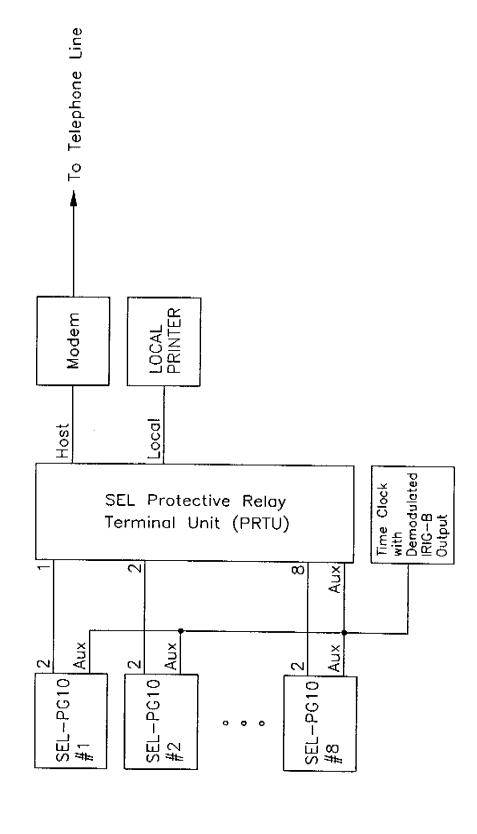
SEL-PG10 EXTERNAL CURRENT AND VOLTAGE CONNECTIONS



SEL-PG10 DC EXTERNAL CONNECTION DIAGRAM (TYPICAL)

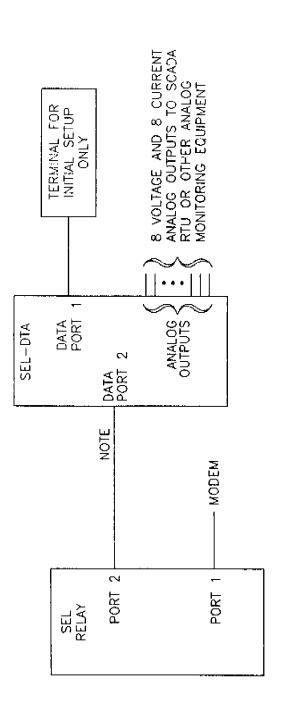
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ALL BE USED SOLELY IN THE PERFORMANCE OF WORK CONTRACTED FOR BY THIS COMPARY.
THE INFORMATION SHALL NOT BE USED OR DISCLOSED BY THE RECIPIENT FOR ANY OTHER PURPOSE
WHATSOEVER.

DWG. NO. 47-0350 DATE: 10-12-88



SEL-PG10 COMMUNICATIONS AND CLOCK CONNECTIONS MULTIPLE UNITS AT ONE LOCATION

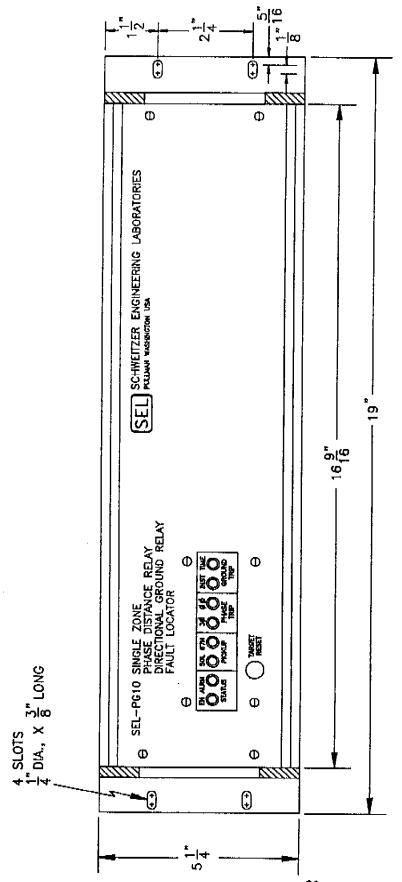
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NOTE: SEL-DTA DISPLAY/TRANSDJCER ADAPTER (DTA)
DATA AND CONTROL POWER

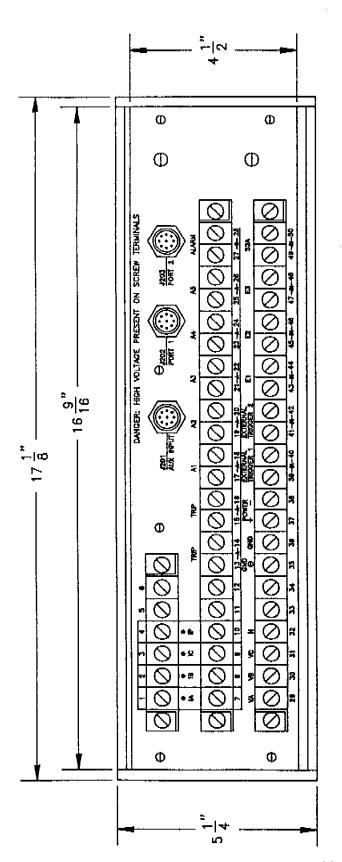
SEL RELAY COMMUNICATIONS DIAGRAM FOR CONNECTION TO THE SEL-DIA

DWG. NO. A7-0413 DATE: 10-07-88



SEL-PG10 HORIZONTAL FRONT PANEL DRAWING

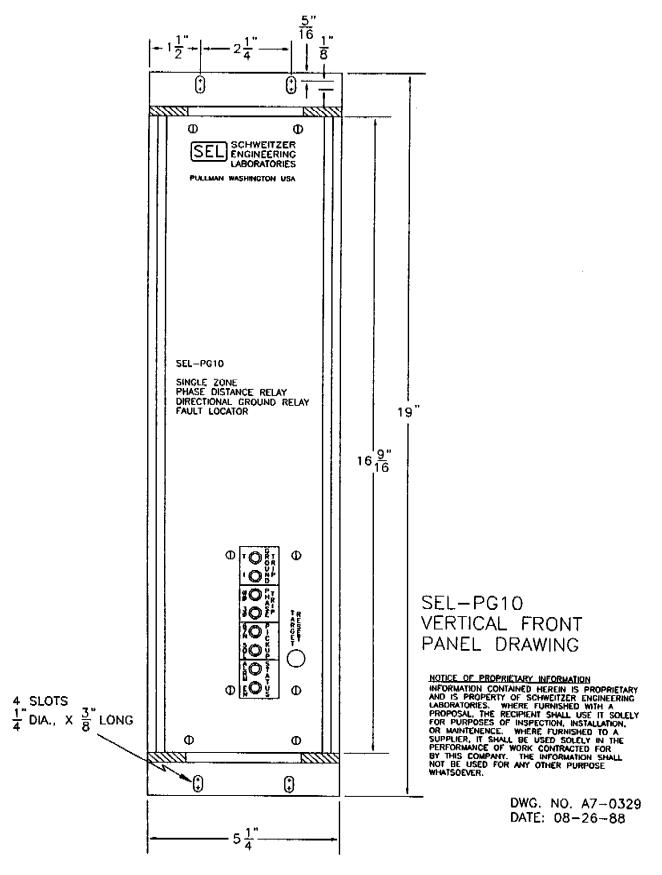
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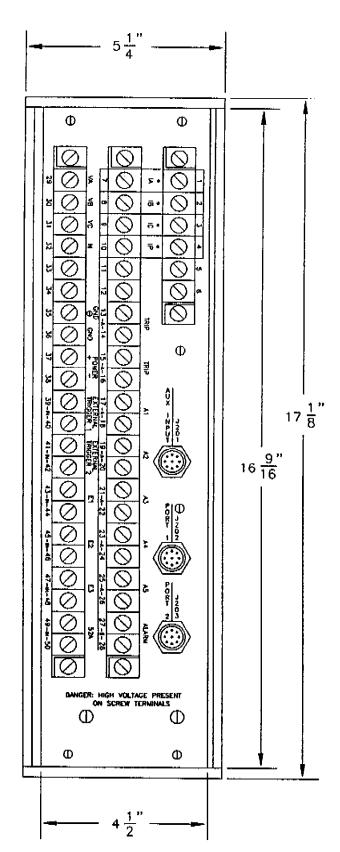


SEL-PG10 HORIZONTAL REAR PANEL DRAWING

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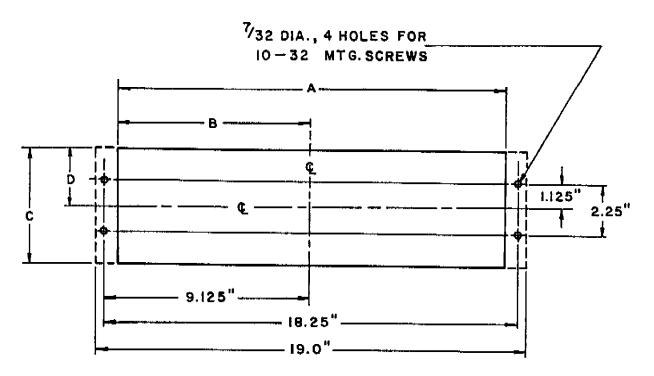




SEL-PG10 VERTICAL REAR PANEL DRAWING

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DWG. NO. A7-0328 DATE: 08-18-88



DIMENSION A:

CASE: 17.00"

CUT OUT: 17. 25" - 17.875" 17.375" PREFERRED

DIMENSION B:

CASE: 8.5"

CUT OUT: 8.625" - 8.9375" 8.688" PREFERRED

DIMENSION C:

CASE: 5.25"

CUT OUT: 5.35" - 5.45"

DIMENSION D:

CASE: 2.625"

CUT OUT: 2.675" - 2.725"

NOTE: ALL INSTRUMENTS MAY BE MOUNTED HORIZONTALLY (AS SHOWN)

OR VERTICALLY.

PANEL CUTOUT AND DRILL PLAN FOR SEMI-FLUSH MOUNTING OF 5.25 INCH HIGH CASE

DWG. NO. A7-0174 DATE 5/11/87 JS REV. 3/9/88

SEL-PGIO DISTANCE RELAY/FAULT LOCATOR COMMAND SUMMARY

<u>Level 0</u>

Answer password prompt (if password protection enabled) to gain ACCESS

access to Level 1. Three unsuccessful attempts pulses ALARM relay.

Level 1

Answer password prompt (if password protection enabled) to gain 2ACCESS

access to Level 2. This command always pulses the ALARM relay.

DAT 2/3/86 sets date to Feb. 3, 1986. Show or set date. DATE setting is overridden when IRIG-B synchronization occurs. Pulses

the ALARM relay and illuminates the ALRM LED momentarily when a

different year is entered than the one previously stored.

Show event record. EVE 1 shows long form of most-recent event. **EVENT**

Show DATE, TIME, EVENT TYPE, FAULT LOCATION, DURATION, and CURRENT HISTORY

for the 12 most-recent faults.

Force immediate execution of time-code synchronization task. IRIG

Show primary current, voltage, real and reactive power. METER runs once. METER N runs N times METER

Return to Access Level O and reset targets to target O. OUIT

Show the relay settings and logic settings -- does not affect the SHOWSET

settings. The logic settings are shown in hexadecimal format for

each.

Show self-test status. STATUS

Show data and set target lights as follows: TARGETS

TAR 1: RELAY WORD TAR 0: Relay Targets

TAR 3: Contact Outputs TAR 2: Contact Inputs

TAR R: Returns to TAR O and clears

Be sure to return TAR O when done, so LEDs display fault targets.

Show or set time. TIM 13/32/00 sets clock to 1:32:00 PM.

setting is overridden when IRIG-B synchronization occurs.

Trigger and save an event record. (Type of event is EXT). TRIGGER

Level 2

TIME

Show or set logic masks MT, MA1-MA5. LOGIC*

Pulses the ALARM relay closed and Show or set passwords. **PASSWORD**

illuminates the ALRM LED momentarily when new passwords are set.

PAS 1 OTTER sets Level 1 password to OTTER.

PAS 2 TAIL sets Level 2 password to TAIL.

Initiate setting procedure. SET*

Use the following to separate commands and their parameters: space, comma, semicolon, colon, slash.

* ALARM relay closes and ALRM target LED illuminates momentarily while new settings are stored in EEPROM and event data buffers are cleared.

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